An algorithm for calculating atomic *D* states with explicitly correlated Gaussian functions

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An algorithm for the variational calculation of atomic D states employing *n*-electron explicitly correlated Gaussians is developed and implemented. The algorithm includes formulas for the first derivatives of the Hamiltonian and overlap matrix elements determined with respect to the Gaussian nonlinear exponential parameters. The derivatives are used to form the energy gradient which is employed in the variational energy minimization. The algorithm is tested in the calculations of the two lowest Dstates of the lithium and beryllium atoms. For the lowest D state of Li the present result is lower than the best previously reported result. © 2011 American Institute of Physics. [doi:10.1063/1.3523348]

I. INTRODUCTION

Very accurate quantum mechanical calculations of the ground and excited states of small atoms have always provided the testing ground for new computational methods for atomic calculations. The testing has been possible due to the availability of very accurate gas-phase spectra of these systems. An important group of states for which such high accuracy experimental data are available are D states. For example, the NIST atomic spectra database¹ among the 182 states of the lithium atom lists ten ^{2}D states which correspond to the electron configurations $1s^2nd$, where $n = 3, 4, \dots, 12$. For the beryllium atom among the 219 levels listed there are $11^{-1}D$ states and 10 ${}^{3}D$ states. The lowest ${}^{1}D$ state corresponds to the electron configuration $1s^2 2p^2$ and the rest to the configurations $1s^2nd^2$, n = 3, 4, ..., 12. The ³D states correspond to the configurations $1s^2nd^2$, $n = 3, 4, \ldots, 12$.

A literature search reveals that only the lowest ${}^{2}D$ state of lithium has been calculated with high accuracy. The best to date variational energy for this state was reported by Yan and Drake² and it is equal to -7.33552354110(43) a.u. (an extrapolated result). There are no calculations with similar accuracy for the *D* states of beryllium. Part of the reason for the lack of calculations of these states is due to the basis set, which for most works concerning atomic levels has involved Hylleraas type functions. These functions, while very effective in the calculations of two- and three-electron atoms,^{2–7} have not yet been extended to four-electron atoms due to difficulties with calculating the Hamiltonian matrix elements.

Another type of basis function that has been very popular in high-accuracy atomic calculations are correlated Gaussian functions that explicitly depend on the interelectron distances. The most accurate results for four- and five-electron atoms have been obtained with those functions.^{8–11} The main advantage of using Gaussians in atomic calculations is due to the simplicity of the Hamiltonian and overlap integrals with those functions, which can be evaluated analytically for an arbitrary number of electrons. However, these functions cannot satisfy the Kato cusps conditions and are too fast decaying at large distances. As the calculations have shown^{8–11} these deficiencies can be effectively remedied by using longer expansions and by performing extensive optimization of the Gaussian nonlinear parameters using the variational approach.

In this work we have derived and implemented algorithms for calculating the Hamiltonian matrix elements with explicitly correlated Gaussian functions for describing Dstates of small atomic systems. We also derived and implemented algorithms for calculating first derivatives of the matrix elements determined with respect to the Gaussian exponents. These derivatives are used to calculate the energy gradient, which is employed in the variational optimization of the Gaussian parameters. The variational energy minimization is greatly accelerated if the energy gradient is available. To test the algorithms, we have performed calculations of two lowest ${}^{2}D$ states of lithium and two lowest ${}^{1}D$ states of beryllium.

In the approach we use in this work we explicitly account for the finite mass of the nucleus in the variational nonrelativistic calculations. This is done by means of using a Hamiltonian that explicitly depends on the masses of all particles including the mass of the nucleus (see Sec. I A). In this way the results change when a different isotope is considered. The approach also allows us to obtain results corresponding to an infinite mass of the nucleus. Such results generated here for lithium in the present work allow for a direct comparison with the calculations performed by Yan and Drake.²

A. The Hamiltonian

We consider an atom with N particles (i.e., N - 1 electrons and a nucleus). We start with the laboratory-frame nonrelativistic Hamiltonian and we separate out the center-of-mass motion. This is done by introducing an internal Cartesian coordinate system centered at the nucleus. The separation of the center-of-mass motion is rigorous and results in the laboratory Hamiltonian becoming a sum of the operator

representing the kinetic energy of the center-of-mass motion and the following "internal" Hamiltonian:

$$\hat{H} = -\frac{1}{2} \left(\sum_{i=1}^{n} \frac{1}{\mu_{i}} \nabla_{\mathbf{r}_{i}}^{2} + \frac{1}{m_{0}} \sum_{i,j=1}^{n} \nabla_{\mathbf{r}_{i}} \cdot \nabla_{\mathbf{r}_{j}} \right) + \sum_{i=1}^{n} \frac{q_{0}q_{i}}{r_{i}} + \sum_{i>j=1}^{n} \frac{q_{i}q_{j}}{r_{ij}},$$
(1)

where n = N - 1, \mathbf{r}_i is the distance between the *i*th electron and the nucleus, m_0 is the nucleus mass and q_0 is its charge, q_i are electron charges, and $\mu_i = m_0 m_i / (m_0 + m_i)$ are electron reduced masses. The Hamiltonian (1) describes the motion of *n* (pseudo)electrons, whose masses have been changed to the reduced masses, in the central field of the charge of the nucleus. This motion is coupled through the Coulombic interactions,

$$\sum_{i=1}^{n} \frac{q_0 q_i}{r_i} + \sum_{i>j=1}^{n} \frac{q_i q_j}{r_{ij}},$$

where $r_{ij} = |\mathbf{r}_j - \mathbf{r}_i|$, and through the mass polarization term,

$$-\frac{1}{2}\sum_{i,j=1\atop i\neq j}^{n}\left(1/m_{0}\right)\nabla_{\mathbf{r}_{i}}\cdot\nabla_{\mathbf{r}_{j}}.$$

II. THE BASIS SET

In this work we consider atomic *D* states corresponding to electronic configurations where one or two electrons of the *n* electron atom is occupying a non-*s* state. Examples of such states include the above-mentioned ${}^{2}D \; 1s^{2}nd^{1}$ states of lithium and the ${}^{1}D$ and ${}^{3}D \; 1s^{2}2s^{1}nd^{1}$ states of beryllium. To describe an atomic state with a single *d* electron one, in principle, needs to use the following explicitly correlated Gaussian function:

$$\phi_k = \left(x_{i_k}^2 + y_{i_k}^2 - 2z_{i_k}^2\right) \exp[-\mathbf{r}' \left(A_k \otimes I_3\right) \mathbf{r}], \qquad (2)$$

where i_k is an electron label whose value can vary from 1 to n and is unique for each basis function. The prime indicates the matrix/vector transpose; this notation is used throughout this work. A_k in Eq. (2) is an $n \times n$ symmetric matrix, \otimes is the Kronecker product, I_3 is a 3×3 identity matrix, and **r** is a 3n vector that has the form

$$\mathbf{r} = \begin{pmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \vdots \\ \mathbf{r}_n \end{pmatrix} = \begin{pmatrix} x_1 \\ y_1 \\ z_1 \\ \vdots \\ x_n \\ y_n \\ z_n \end{pmatrix}.$$
 (3)

We will denote $(A_k \otimes I_3)$ in Eq. (2) as A_k . However, in the wave functions of some of the *D* states there can be components corresponding to two electrons being in *p* states coupling to a *D* state. For example, the lowest 1D state of

beryllium is dominated by the $1s^22p^2$ configuration. Also, the lowest 2D state of lithium has a non-negligible contribution from a similar configuration $(1s^12p^2)$.² Thus, the Gaussian basis set that can best capture all the angular coupling effects in *D* states is the following basis:

$$\phi_k = \left(x_{i_k} x_{j_k} + y_{j_k} y_{i_k} - 2z_{i_k} z_{j_k} \right) \exp[-\mathbf{r}'(A_k \otimes I_3)\mathbf{r}], \qquad (4)$$

where electron indices i_k and j_k are either equal or not equal to each other.

We use a general quadratic form $\mathbf{r'W}_k\mathbf{r}$ in place of $(x_{i_k}x_{j_k} + y_{i_k}y_{j_k} - 2z_{i_k}z_{j_k})$ allowing for a more generalized approach in deriving the matrix elements. With that, our basis functions are

$$\phi_k = (\mathbf{r}' \mathbf{W}_k \mathbf{r}) \exp[-\mathbf{r}' \mathbf{A}_k \mathbf{r}], \tag{5}$$

where \mathbf{W}_k is a sparse $3n \times 3n$ symmetric matrix that for $i_k = j_k$ comprises only three nonzero elements: $W_{3(i_k-1)+1,3(i_k-1)+1} = 1,$ $W_{3(i_k-1)+2,3(i_k-1)+2} = 1,$ and $W_{3(i_k-1)+3,3(i_k-1)+3} = -2$, and for $i_k \neq j_k$ it comprises six elements: $W_{3(i_k-1)+1,3(j_k-1)+1} = W_{3(j_k-1)+1,3(i_k-1)+1} = \frac{1}{2}$, $W_{3(i_k-1)+2,3(j_k-1)+2} = W_{3(j_k-1)+2,3(i_k-1)+2} = \frac{1}{2},$ and $W_{3(i_k-1)+3,3(j_k-1)+3} = W_{3(j_k-1)+3,3(i_k-1)+3} = 1.$ It should be noted that, in general, we could have used a nonsymmetric matrix (for $i_k \neq j_k$) \mathbf{W}_k with only three nonzero elements (yielding the same quadratic form) since there are only three terms in Eq. (4). However, in practice it is much more convenient to deal with symmetric \mathbf{W}_k matrices as the derivations of matrix elements becomes considerably simpler in this case.

As the basis functions used in describing bound states must be square integrable, restrictions must be imposed on the A_k matrices. Each A_k matrix must be positive definite. Rather than restricting the A_k matrix elements, which usually leads to cumbersome constraints, we use the following Cholesky factored form of A_k : $A_k = L_k L'_k$, where L_k is a lower triangular matrix. With this representation, A_k is automatically positive definite for any values of L_k ranging from ∞ to $-\infty$. Thus, the variational energy minimization with respect to the L_k parameters can be carried out without any restrictions. It should be noted that the $L_k L'_k$ representation of A_k matrix does not limit the flexibility of basis functions, because any symmetric positive matrix can be represented in a Cholesky factored form.

The linear expansion coefficients of the wave function in terms of the basis functions and the elements of the L_k matrices are optimization variables. Also, for each basis function the i_k and j_k indices are optimized. This optimization is only done once for each basis function when the function is first added to the basis set.

III. THE HAMILTONIAN INTEGRALS AND THE GRADIENT

In order to fully exploit the sparsity of the \mathbf{W}_k matrices and make the calculation more efficient, three cases have been distinguished in the calculation of the Hamiltonian and overlap integrals. The first case concerns the integrals between the basis functions with $i_k \neq j_k$, the second case the integrals for functions with $i_k = j_k$, and the third case the mixed integrals. Similar separation is applied in the calculation of the energy gradient. As the integrals and the gradient are similar to those published before for atomic states with two p electrons,^{12,13} we only present the final formulas in the Appendix.

As the total atomic wave function must be antisymmetric with respect to the permutation of the electron labels an appropriate symmetry projection needs to be applied to each basis function. In this work we use the spin-free formalism. The Young projection operator, \hat{Y} , which imposes proper symmetry, has to be applied only to the spatial part of the wave function and thus to each basis function, $\hat{Y}\phi_k$. \hat{Y} is a linear combination of permutational operators, \hat{P}_{ν} , and, as the Hamiltonian is invariant with respect to all permutations of the electrons, in the calculation of the overlap and Hamiltonian matrix elements it is easy to arrange that the permutational operators are applied to the ket only. In brief, the ket functions in those matrix elements are operated on with the permutation operator $\hat{P} = \hat{Y}^{\dagger}\hat{Y}$ (the dagger stands for conjugate), where the \hat{Y} operator can be derived using the appropriate Young tableaux for the state under consideration. For lithium in a ${}^{2}D$ and beryllium in a ${}^{1}D$ state the Young operators can be chosen as $\hat{Y} = (\hat{1} + \hat{P}_{34})(\hat{1} - \hat{P}_{23})$ and $\hat{Y} = (\hat{1} - \hat{P}_{45})(\hat{1} - \hat{P}_{23})(\hat{1} + \hat{P}_{24})(\hat{1} + \hat{P}_{35})$, respectively, where the nucleus is labeled as 1, and the electrons are labeled as 2, 3, 4, 5, $\hat{1}$ is the identity operator, and \hat{P}_{ij} is the permutation of the the *i*th and *j*th electron.

A. Total energy and energy gradient

The optimization of the linear expansion coefficients, the L_k Gaussian parameters, and the i_k and j_k indices, is performed in this work through the minimization of the standard Rayleigh–Ritz variational energy functional. In the minimization the energy gradient is employed. The calculation for each state is performed independently from other states and the parameters of the basis functions are optimized specifically for that particular state. In the process of generating the basis set, we start with a small randomly selected set of functions and this set is then grown by incremental additions of small groups of functions. The added functions are generated randomly based on the actual distribution of nonlinear parameters of the functions already present in the basis set. At this step a significant number of random candidates are generated and only those that give the best improvement of the total energy are selected. When a new group of functions is added to the set their nonlinear parameters are optimized with the gradientbased method. After this is finished the nonlinear parameters of the entire basis set (one function at a time) are reoptimized.

IV. NUMERICAL TESTS

The first test of the approach developed in this work concerns the lowest ${}^{2}D$ state of lithium. As mentioned this state was calculated before by Yan and Drake.² As their calculation was performed with an infinite mass of the lithium nucleus, we also first carried a calculation setting the mass of the nucleus (m_0) to infinity. The convergence of the total energy with the number of Gaussian functions in the ba-

TABLE I. The convergence of the total variational energy of the lowest ${}^{2}D$ state of lithium with the number of Gaussians obtained in the present infinitenuclear mass variational calculations. The energies are in hartrees.

Basis set size	Energy		
1900	-7.335 523 530 70		
2300	-7.335 523 538 22		
2700	-7.335 523 540 89		
3100	-7.335 523 541 96		
3500	-7.335 523 542 51		
3900	-7.335 523 542 82		
1673 ^a	-7.335 523 540 35		
$\infty^{a,b}$	-7.335 523 541 10(43)		

^aFrom Ref. 2.

^bThe energy obtained by extrapolating to infinity in terms of the parameter Ω used in the integral formulas by Yan and Drake (Ref. 2).

sis set is shown in Table I. As one notices, the energy is converged to about ten significant figures. The energy value obtained in the present calculations with 3900 Gaussians of -7.33552354282(60) a.u. is lower than the previous best variational upper bound of Yan and Drake² by about 2×10^{-9} hartree. The Yan and Drake energy is obtained in our calculations with about 2600 Gaussians in the basis set. The lithium test clearly shows that Gaussians can effectively describe the *D* states of small atomic systems. Also, the agreement between Yan and Drake's and our results give us confidence that the algorithm and its implementation works correctly.

The next test concerns the energy differences between the energies of the two lowest ^{2}D states of ^{7}Li corresponding to the electron configurations $1s^23d^1$ and $1s^24d^1$ and the ⁷Li $1s^22s^1$ ground state energy. These energy differences can be compared with the experimental values taken from the NIST atomic spectra database.¹ Here we used a finite nuclear mass approach, which is possible in our scheme. The convergence of the total nonrelativistic energies with the number of basis functions obtained in those calculations are shown in Table II. We also show in Table II the energy of the ⁷Li ground state obtained in our previous work¹⁴ and the energy of ⁷Li⁺ calculated in this work. The latter value is used to determine the ⁷Li nonrelativistic ionization potential (IP). The reason we need the ⁷Li IP is to compare it with the relative energies of the ${}^{2}D$ states determined with respect to the energy of the ground state. Such a comparison must show that in the limit of exciting the d electron in ⁷Li to increasingly higher ^{2}D states, the relative energy should converge to the ⁷Li IP as the electron becomes removed from the atom. Naturally, as only two ^{2}D states are calculated in this work and not a wider range of the Rydberg $1s^2nd^1$ states is considered, the consistency of the results and not the convergence will be tested.

It should also be mentioned that, as the present results do not include relativistic corrections, the agreement with the experimental values is not expected to be perfect. This is why we need the IP value. If the algorithm implemented in this work is correct, the difference between the experimental and calculated nonrelativistic IPs should be similar to the differences between the calculated relative energies of the two 2D states of 7Li and their corresponding experimental counterparts. The

TABLE II.	The convergence of the total	variational finite mass	s energies of the two lowe	st ^{2}D states of	'Li with the number o	f Gaussians. The to	tal energies
are in hartre	es and the ionization potential	s (IP) in cm^{-1} .					

No. of basis functions	7 Li 1 $s^{2}3d^{1}$	7 Li 1 $s^{2}4d^{1}$	$^{7}\text{Li}^{+} 1s^{2}$	⁷ Li 1 <i>s</i> ² 2 <i>s</i> ¹
2600	-7.334 927 304 45	-7.310 595 236 10		
2800	-7.334 927 304 88	-7.310 595 237 62		
3000	-7.334 927 305 14	-7.310 595 238 65		
3200	-7.334 927 305 41	-7.310 595 239 66		
3400	-7.334 927 305 59	-7.310 595 240 28		
3600	-7.334 927 305 75	-7.310 595 240 76		
10000 ^a				-7.477 451 930 7
300 ^b			-7.279 321 516 83	
400			-7.279 321 519 40	
500			-7.279 321 519 72	
Energy difference ^c	31280.54	36620.81	43484.60	
Experiment ^d	31283.08	36623.38	43487.15	
Δ^{e}	-2.54	-2.57	-2.55	

^aFrom Ref. 14.

^bCalculations for ⁷Li⁺ have been performed in this work.

^cCalculated relative to the ground 1s² ²s¹ state of ⁷Li. For the ⁷Li 2D states the energies obtained with 3600 Gaussians were used. For ⁷Li⁺ the energy obtained with 500 Gaussians was used.

dFrom Ref. 1.

eDetermined as the calculated energy difference minus the experimental energy difference.

results presented in Table II show that they are indeed very similar. The IP of ⁷Li calculated at the nonrelativistic level of 43 484.60 cm⁻¹ is lower than the experimental value by 2.55 cm⁻¹. This is very close to the differences between the experimental and calculated relative energies of the two ²D states, which are 2.54 and 2.57 cm⁻¹, respectively. Clearly, the relativistic contribution to the relative energies of the ²D states of ⁷Li from the Rydberg *d* electron is very small. It should be said that the present finite-mass calculations of the two ²D states of ⁷Li are the first ever performed. Also, these are the first calculations that described the $1s^24d^{12}D$ ⁷Li state with a similar accuracy as the lower $1s^23d^{12}D$ state.

The last test concerns the two lowest ${}^{1}D$ states of the beryllium atom (9 Be). This test is performed to show the capability of the method developed in this work to describe

D states of atoms with more than three electrons—the task which is still out of reach for other types of explicitly correlated basis functions. The results of the beryllium calculations are shown in Table III. Here we also show the convergence of the total nonrelativistic energies for the ⁹Be $1s^22p^2$ and $1s^22s^13d^{1-1}D$ states with the number of basis functions and the relative energies with respect to the ground $1s^22s^{2-1}S$ state. As in Table II, the results also include the IP value, as well as the experimental values taken from the NIST atomic spectra database.¹

First, as one notices, the total variational energies for beryllium ${}^{1}D$ states are not as well converged with the number of basis functions as the energies for the two ${}^{2}D$ states of lithium. The lowest energy values corresponding to configurations $1s^{2}2p^{2}$ and $1s^{2}2s^{1}3d^{1}$, which we obtained in

TABLE III. The convergence of the total variational finite mass energies of the two lowest ${}^{1}D$ states of ${}^{9}Be$ with the number of Gaussians. The total energies are in hartrees and the energy differences with respect to the ground state in cm⁻¹.

No. of basis functions	⁹ Be $1s^2 2p^2$	⁹ Be $1s^2 2s^1 3d^1$	${}^{9}\text{Be}^{+} 1 s^{2} 2 s^{1}$	⁹ Be $1s^2 2s^2$
1200	-14.407 341 480 5	-14.372 916 534 2		
1300	-14.407 343 628 4	-14.372 918 282 8		
1400	-14.407 345 233 1	-14.372 919 011 1		
1500	-14.407 346 376 9	-14.372 920 572 8		
1600	-14.407 347 946 1	-14.372 921 316 6		
1700	-14.407 347 875 3	-14.372 921 585 6		
1800	$-14.407\ 348\ 488\ 2$	-14.372 922 259 3		
10000 ^a				-14.666 435 504
8000 ^b			-14.323 863 494 4	
Energy difference ^c	56863.03	64418.71	75185.87	
Experiment ^d	56882.43	64428.31	75192.64	
Δ^{e}	-19.40	-9.60	-6.77	

^aFrom Ref. 15.

^bFrom Ref. 16.

^cCalculated relative to the ground $1s^22s^2$ state of ⁹Be. For the ¹D Be states the energies obtained with 1800 Gaussians were used.

^dFrom Ref. 1.

eDetermined as the calculated energy difference minus the experimental energy difference.

our calculations are $-14.407\ 348\ 488\ 2$ and $-14.372\ 922\ 259\ 3$ a.u., respectively. We estimate that the remaining uncertainty for these values is of the order of 10^{-6} a.u. It would take several thousand Gaussians to converge them to the level of accuracy reached for lithium and such calculations will be carried out in the future. However, even with the present results, the agreement with the experiment for the relative energies is very good. Also the difference between the calculated relative energies and the experimental energies seems to converge to the IP calculated based on very accurate total energies of ⁹Be and ⁹Be⁺ taken from our previous works.^{15,16} The results show that, unlike for lithium, the relativistic correction to IP of ⁹Be is almost three times smaller than for the relative energy of the lowest ¹D state of this atom.

V. SUMMARY

The following has been accomplished in this work.

- 1. An algorithm for nonrelativistic variational calculations of atomic *D* states has been developed and implemented.
- 2. The approach has been used to obtain new improved upper bound to the variational infinite-mass energy of the lowest ${}^{2}D$ state of lithium.
- 3. High-accuracy lithium calculations have also been performed for the two lowest ${}^{2}D$ states of the ${}^{7}Li$ isotope using the finite-mass regime enabled by the approach. The results show very good agreement with the experiment.
- 4. It has been demonstrated that the approach can be used to carry out calculations of *D* states of an atomic system with more than three electrons.

The work presented here will be extended in the future to study wider range of Rydberg D states of the leading isotopes of lithium and beryllium. The approach will also be used in calculations of D states of atoms and atomic ions with more than four electrons.

APPENDIX A: MATRIX ELEMENTS AND THE GRADIENT

Below, we show the expressions for the Hamiltonian and overalp matrix elements and the corresponding derivatives with respect to the L_k matrix elements. We do not show how those quantities have been derived because the procedure was very similar to that presented in our previous works.^{12,13}

Let us first define a quantity common to the overlap, kinetic, and potential energy matrix elements:

$$\eta = \operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{W}_l \right], \tag{A1}$$

and a quantity common only to the kinetic energy matrix element:

$$\tau = \operatorname{tr} \left[A_{kl}^{-1} A_k M A_l \right]. \tag{A2}$$

In Eq. (A2) *M* is the mass matrix whose diagonal elements are set to $1/(2m_1)$, $1/(2m_2)$, ..., $1/(2m_n)$, while the off-diagonal elements are set to $1/(2m_0)$. Again, m_0 is the mass of the nucleus and m_1, \ldots, m_n are the electron masses. Next we define

$$\lambda = \operatorname{tr}\left[A_{kl}^{-1}J\right],\tag{A3}$$

common only to the potential energy matrix element, where matrix J has the following simple structure:

$$J = \begin{cases} E_{ii}, & i = j \text{ for } r_i \\ E_{ii} + E_{jj} - E_{ij} - E_{ji}, & i \neq j \text{ for } r_{ij} \end{cases}$$
 (A4)

and E_{ij} is a matrix with 1 in the *i*, *j*th position and 0's elsewhere.

In addition to these quatities we also define operations used to determine the gradient formulas. First, the "vech" operation transforms an $n \times n$ matrix into an n(n + 1)/2-component vector and, second, the transformation matrix, \mathcal{T} , formed by the first derivatives of the elements of vech of a $3n \times 3n$ matrix \mathbf{L}_k (\mathbf{L}_l) with respect to the elements of vech of $n \times n$ matrix L_k (L_l). \mathcal{T} is defined as

$$\mathcal{T} = \frac{d \operatorname{vech} \mathbf{L}_k \operatorname{(vech} L_k)}{d \operatorname{(vech} L_k)'} \equiv \frac{d \operatorname{vech} \mathbf{L}_l \operatorname{(vech} L_l)}{d \operatorname{(vech} L_l)'}.$$
 (A5)

The overlap integral for ϕ_k and ϕ_l basis functions is

$$\langle \phi_k | \phi_l \rangle = \frac{1}{2} \pi^{3n/2} |A_{kl}|^{-3/2} \eta,$$
 (A6)

and its derivatives with respect to vech L_k and vech L_l are

$$\frac{\partial \langle \phi_{k} | \phi_{l} \rangle}{\partial \operatorname{vech} L_{k}} = -\frac{1}{2} \pi^{3n/2} |A_{kl}^{-1}|^{3/2} \left\{ \frac{3}{2} \operatorname{vech} \left((A_{kl}^{-1} + A_{kl}^{-1}') L_{k} \right) \eta + \operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{l} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{l} \mathbf{A}_{kl}^{-1} \right)' \mathbf{L}_{k} \right) \mathcal{T} + \operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{l} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \right)' \mathbf{L}_{k} \right) \mathcal{T} \right\},$$

$$\frac{\partial \langle \phi_{k} | \phi_{l} \rangle}{\partial \operatorname{vech} L_{l}} = -\frac{1}{2} \pi^{3n/2} |A_{kl}^{-1}|^{3/2} \left\{ \frac{3}{2} \operatorname{vech} \left((A_{kl}^{-1} + A_{kl}^{-1})' L_{l} \right) \eta + \operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{l} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \right)' \mathbf{L}_{l} \right) \mathcal{T} + \operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{l} \mathbf{A}_{kl}^{-1} \right) \right) \right\}.$$
(A7)
$$\frac{\partial \langle \phi_{k} | \phi_{l} \rangle}{\partial \operatorname{vech} L_{l}} = -\frac{1}{2} \pi^{3n/2} |A_{kl}^{-1} |^{3/2} \left\{ \frac{3}{2} \operatorname{vech} \left((A_{kl}^{-1} + A_{kl}^{-1}) L_{l} \right) \eta + \operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{l} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{l} \mathbf{A}_{kl}^{-1} \right\} \right) \right) (A_{kl} \left\{ A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \right\} \right\} .$$
(A7)

The kinetic energy matrix element is

$$\mathbf{T}_{kl} = \langle \phi_k | - \nabla_{\mathbf{r}}' \mathbf{M} \nabla_{\mathbf{r}}' | \phi_l \rangle = \pi^{3n/2} |A_{kl}|^{-3/2} \{ 3\eta \tau + 2 \big(\operatorname{tr} \big[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{W}_l \mathbf{A}_{kl}^{-1} \mathbf{A}_k \mathbf{M} \mathbf{A}_l \big] + \operatorname{tr} \big[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{M} \mathbf{W}_l \big] \\ - \operatorname{tr} \big[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{A}_k \mathbf{M} \mathbf{W}_l \big] - \operatorname{tr} \big[\mathbf{A}_{kl}^{-1} \mathbf{W}_l \mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{M} \mathbf{A}_l \big] \\ + \operatorname{tr} \big[\mathbf{A}_{kl}^{-1} \mathbf{W}_l \mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{A}_k \mathbf{M} \mathbf{A}_l \big] \big\},$$
(A9)

and its derivative with respect to vech L_k and vech L_l are

$$\begin{split} \frac{\partial T_{kl}}{\partial \operatorname{vech} L_k} &= \frac{\partial (\phi_k| - \nabla_k^{*} \mathbf{M} \nabla_k^{*} (\phi_k)}{\partial \operatorname{vech} (L_k)} \\ &= -\pi^{3k/2} |A_{kl}|^{-3/2} \left\{ \frac{3}{2} \operatorname{vech} \left((A_{kl}^{-1} + A_{kl}^{-1})_{L_k} \right) \left(3\eta \tau + 2 \left(\operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{A}_k \mathbf{M} \mathbf{A}_l \right] + \operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{A}_k \mathbf{M} \mathbf{M}_l \right] + \operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{A}_k \mathbf{M} \mathbf{M}_l \right] \\ &+ \operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{A}_k \mathbf{M} \mathbf{M}_l \right] + \operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \right] \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \right] \mathbf{V}_k \mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \right] \mathbf{V}_k \mathbf{A}_{kl}^{-1} \mathbf{V}_k \mathbf{A}_{kl}^{-1} \mathbf{V}_k \mathbf{A}_{kl}^{-1} \right] \mathbf{V}_k \mathbf{A}_{kl}^{-1} \mathbf{V}_k \mathbf{A}_{kl}^{-1} \mathbf{V}_k \mathbf{A}_{kl}^{-1} \right] \mathbf{V}_k \mathbf{A}_{kl}^{-1} \mathbf{V}_k \mathbf{A$$

$$\begin{split} \frac{\partial \mathsf{T}_{kl}}{\partial \operatorname{vech} L_l} &= \frac{\partial \langle \phi_k | - \mathsf{V}_{k}^{l} \mathsf{M} \mathsf{V}_{k}^{l} | \phi_k \rangle}{\partial \operatorname{vech} L_l} \\ &= -\pi^{3d/2} | A_{kl} |^{-3/2} \left\{ \frac{3}{2} \operatorname{vech} \left((A_{kl}^{-1} + A_{kl}^{-1}) L_l \right) \left(\eta \tau + 2 \left(\operatorname{tr} \left[A_{kl}^{-1} \mathsf{W}_{k} A_{kl}^{-1} \mathsf{W}_{k} \mathsf{M}_{kl} \right] + \operatorname{tr} \left[A_{kl}^{-1} \mathsf{W}_{k} \mathsf{M}_{kl} \right] + \operatorname{tr} \left[A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{M}_{kl} \right] \right) \\ &+ 3\tau \left(\operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \right) L_l \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \right) L_l \right) \mathcal{T} \\ &+ 3\eta \left(\operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{A}_{kl} \mathsf{M}_{kl} \mathsf{A}_{kl}^{-1} \right) L_l \right) \right) \\ &+ 2 \left(\operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{A}_{kl} \mathsf{M}_{kl} \mathsf{A}_{kl}^{-1} \right) L_l \right) \\ &- \operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \right) L_l \right) \right) \\ &+ 2 \left(\operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \right) L_l \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \right) L_l \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \right) L_l \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \right) L_l \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \right) L_l \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{A}_{k} \mathsf{M}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{A}_{k} \mathsf{M}_{k} \mathsf{A}_{kl}^{-1} \right) L_l \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1} + (A_{kl}^{-1} \mathsf{W}_{k} \mathsf{A}_{kl}^{-1}$$

And finally, the potential energy matrix element is

$$\mathsf{V}_{kl} = \langle \phi_k | \frac{1}{r_{ij}} | \phi_l \rangle = 2\pi^{(3n-1)/2} |A_{kl}|^{-3/2} \lambda^{-1/2} \left\{ \frac{1}{2} \eta_- \frac{1}{6} \lambda^{-1} \left(\operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{J} \right] + \operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_l \mathbf{A}_{kl}^{-1} \mathbf{J} \right] + \operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_l \mathbf{A}_{kl}^{-1} \mathbf{J} \right] \right\} + \frac{1}{20} \lambda^{-2} \left(2 \operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{J} \mathbf{A}_{kl}^{-1} \mathbf{W}_l \mathbf{A}_{kl}^{-1} \mathbf{J} \right] + \operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_k \mathbf{A}_{kl}^{-1} \mathbf{J} \right] \right\},$$
(A12)

and its derivatives with respect to vech L_k and vech L_l are

$$\frac{\partial \mathsf{V}_{kl}}{\partial \operatorname{vech} L_k} = \frac{\partial \langle \phi_k | \frac{1}{r_{ij}} | \phi_l \rangle}{\partial \operatorname{vech} L_k} \\ = 2\pi^{(3n-1)/2} |A_{kl}|^{-3/2} \lambda^{-1/2} \left\{ \left(\frac{1}{2} \lambda^{-1} \operatorname{vech} \left(\left(A_{kl}^{-1} J A_{kl}^{-1} + \left(A_{kl}^{-1} J A_{kl}^{-1} \right)' \right) L_k \right) - \frac{3}{2} \operatorname{vech} \left(\left(A_{kl}^{-1} + A_{kl}^{-1} \right) L_k \right) \right) \right\}$$

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$$\times \left(\frac{1}{2}\eta - \frac{1}{6}\lambda^{-1}\left(\operatorname{tr}\left[\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{l}\mathbf{A}_{kl}^{-1}\mathbf{J}\right] + \operatorname{tr}\left[\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{J}\right]\right) \right)$$

$$+ \frac{1}{2}\left(\operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1} + \left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{l}\mathbf{A}_{kl}^{-1}\right)'\right)\mathbf{L}_{k}\right)$$

$$+ \operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1} + \left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)'\mathbf{L}_{k}\right)\right)\mathcal{T}$$

$$+ \frac{1}{6}\lambda^{-1}\left(\operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{l}\mathbf{A}_{kl}^{-1}\mathbf{J}\mathbf{A}_{kl}^{-1} + \left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)'\mathbf{L}_{k}\right)\right)\mathcal{T}$$

$$+ \operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1} + \left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{l}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)'\mathbf{L}_{k}\right)$$

$$+ \operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1} + \left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)'\mathbf{L}_{k}\right)$$

$$+ \operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1} + \left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)'\mathbf{L}_{k}\right)$$

$$+ \operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1} + \left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)'\mathbf{L}_{k}\right)$$

$$+ \operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1} + \left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)'\mathbf{L}_{k}\right)$$

$$+ \operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1} + \left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)'\mathbf{L}_{k}\right) \right) \mathcal{T}$$

$$+ \operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1} + \left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)'\mathbf{L}_{k}\right) \right)$$

$$+ \operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1}\right)'\mathbf{L}_{k}\right) \right) \mathcal{T}$$

$$- \frac{1}{6}\lambda^{-2}\operatorname{vech}\left(\left(\mathbf{A}_{kl}^{-1}\mathbf{A}_{kl}\mathbf{M}_{kl}^{-1}\mathbf{M}_{k}\mathbf{A}_{kl}^{-1}\mathbf{W}_{k}\mathbf{A}_{kl}^{-1$$

$$\begin{split} \frac{\partial \mathsf{V}_{kl}}{\partial \operatorname{vech} L_{l}} &= \frac{\partial \langle \mathsf{d} \mathsf{k} | \frac{1}{r_{l}} | \phi \mathsf{h} \rangle}{\partial \operatorname{vech} L_{l}} \\ &= 2\pi^{(3n-1)/2} |A_{kl}|^{-3/2} \lambda^{-1/2} \left\{ \left(\frac{1}{2} \lambda^{-1} \operatorname{vech} \left((A_{kl}^{-1} J A_{kl}^{-1} + (A_{kl}^{-1} J A_{kl}^{-1})') L_{l} \right) - \frac{3}{2} \operatorname{vech} \left((A_{kl}^{-1} + A_{kl}^{-1})' L_{l} \right) \right) \right. \\ &\times \left(\frac{1}{2} \eta - \frac{1}{6} \lambda^{-1} \left(\operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{l} \mathbf{A}_{kl}^{-1} \mathbf{J} \right] + \operatorname{tr} \left[\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{J} \right] \right) \right) \\ &+ \frac{1}{2} \left(\operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{l} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{l} \mathbf{A}_{kl}^{-1} \right) \right) \mathcal{I} \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1}) \right) \mathcal{I} \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1}) \right) \mathcal{I} \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1}) \right) \mathcal{I} \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1}) \right) \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1}) \right) \mathcal{I} \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathbf{M}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1}) \right) \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathbf{M}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1}) \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathbf{M}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1}) \right) \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathbf{M}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} + (\mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \right) \right) \\ &+ \operatorname{vech} \left((A_{kl}^{-1} \mathbf{M}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1} \mathbf{W}_{k} \mathbf{A}_{kl}^{-1}$$

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