

Variational method for excited states

The Ritz theorem considered in the previous lecture can also be generalized for excited states. The generalized form reads as follows: The expectation value of the Hamiltonian is stationary in the neighborhood of its discrete eigenvalues.

Proof:

Let us calculate the increment δE of the mean value using the relation $E\langle \psi | \psi \rangle = \langle \psi | H | \psi \rangle$ when ψ is changed from ψ to $\psi + \delta\psi$. Here $\delta\psi$ is assumed to be an infinitely small variation. Neglecting terms of orders higher than linear in $\delta\psi$ we obtain:

$$\delta E \langle \psi | \psi \rangle + E \delta \langle \psi | \psi \rangle = \delta \langle \psi | H | \psi \rangle$$

or

$$\langle \psi | \psi \rangle \delta E = -E \langle \delta\psi | \psi \rangle - E \langle \psi | \delta\psi \rangle + \langle \delta\psi | H | \psi \rangle + \langle \psi | H | \delta\psi \rangle$$

$$\langle \psi | \psi \rangle \delta E = \langle \delta\psi | H - E | \psi \rangle + \langle \psi | H - E | \delta\psi \rangle$$

The mean value E is stationary if $\delta E = 0$ for any infinitesimal $\delta\psi$. That is, if

$$\langle \delta\psi | H - E | \psi \rangle + \langle \psi | H - E | \delta\psi \rangle = 0$$

If $\delta\psi$ is chosen to be $\epsilon(H-E)\psi$, where ϵ is an infinitesimal real number, the above equation implies that the norm of the function $(H-E)\psi$ is zero, and thus $(H-E)\psi$ must be a null function, or in other words it must satisfy the equation $H\psi = E\psi$. Therefore the mean value E is stationary if (and only if) ψ is an eigenstate of H and the stationary value E is the corresponding eigenvalue of H .

End of proof.

The generalized Ritz theorem allows to determine (approximately) the ground and excited energies of a quantum system. If $E(\{d\})$, where $\{d\}$ are some parameters of the trial function, has several extrema, they are approximate values of certain energy levels E_n .

In practical applications the wave function is commonly represented as a linear combination of a finite number of independent functions $\phi_i(x_i)$ [Rayleigh-Ritz method]

$$\Psi = \sum_{i=1}^N c_i \phi_i(x_i)$$

Function $\phi_i(x_i)$ do not have to be mutually orthogonal. In fact, in practical applications they are often not orthonormal. However, this set of N functions can always be made orthonormal, if necessary, by means of the Gram-Schmidt orthogonalization procedure. The use of the variational method then amounts to solving an eigenvalue problem in a subspace spanned by $\{\phi_i(x_i)\}$. The restriction to a finite-dimensional subspace greatly simplifies the problem. Instead of finding the solution (Ψ_{exact}) in an infinitely-dimensional Hilbert space, we can find a minimum (with respect to $\{c_i\}$) in N dimensions. (it may be useful to find a minimum with respect to $\{d_i\}$, if feasible).

For simplicity let us assume that all ϕ_i 's and c_i 's are real (although the method also works for complex functions ϕ_i and coefficients c_i).

We require that the approximate wave function to remain normalized regardless of what happens to c_i 's :

$$\langle \psi | \psi \rangle = 1$$

This introduces a constraint into our minimization of $\langle \psi | H | \psi \rangle$ with respect to c_i 's. The constrained minimization can be handled by means of the Lagrange multiplier method (see appendix in order to refresh your memory about this method). We form a new quantity :

$$F(c_1, \dots, c_N; \lambda) = \langle \psi | H | \psi \rangle - \lambda (\langle \psi | \psi \rangle - 1)$$

and find an unconstrained minimum with respect to both $\{c_i\}$ and λ :

$$\frac{\partial F}{\partial c_k} = \frac{\partial F}{\partial \lambda} = 0 \quad k=1, \dots, n$$

which immediately yields $\langle \psi | \psi \rangle - 1 = 0$

Inserting the liner combination $\sum_{i=1}^n c_i \phi_i$ in place of ψ gives

$$\begin{aligned} \frac{\partial}{\partial c_k} \left[\langle \sum_i c_i \phi_i | H | \sum_j c_j \phi_j \rangle - \lambda (\langle \sum_i c_i \phi_i | \sum_j c_j \phi_j \rangle - 1) \right] &= \\ = \frac{\partial}{\partial c_k} \sum_{ij} c_i c_j [\langle \phi_i | H | \phi_j \rangle - \lambda \langle \phi_i | \phi_j \rangle] & \end{aligned}$$

Let us denote $\langle \phi_i | H | \phi_j \rangle = H_{ij}$ and $\langle \phi_i | \phi_j \rangle = S_{ij}$
Then taking into account that $\frac{\partial c_i c_j}{\partial c_k} = \delta_{ik} c_j + \delta_{jk} c_i$,

$$\frac{\partial F}{\partial c_k} = \sum_j c_j [\langle \phi_k | H | \phi_j \rangle - \lambda \langle \phi_k | \phi_j \rangle] + \sum_i c_i [\langle \phi_k | H | \phi_i \rangle - \lambda \langle \phi_k | \phi_i \rangle]$$

or

$$\sum_j H_{kj} c_j = \lambda \sum_j S_{kj} c_j$$

We can now recognize the generalized eigenvalue problem:

$$H\vec{c} = \lambda S\vec{c}$$

where H and S are $N \times N$ matrices (matrix representations of the Hamiltonian and overlap in subspace $\{\phi_i\}$) and \vec{c} is a column vector

$$\vec{c} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_N \end{pmatrix}$$

There are N solutions of the generalized eigenvalue problem, that is there are N pairs λ, \vec{c} . We can label them with an index

$$\lambda_i \vec{c}^{(i)} \quad i=1, \dots, N$$

The relationship between the eigenvalues of the truncated problem $H\vec{c} = \lambda S\vec{c}$ and the eigenvalues E_i of the original Hamiltonian is elucidated by the Mini-Max theorem (proved in appendix), which states that if $\{\phi_i\}$ is a set of N linearly independent functions then

$$E_1 \leq \lambda_1 \quad E_2 \leq \lambda_2 \quad E_3 \leq \lambda_3 \quad \dots \quad E_N \leq \lambda_N$$

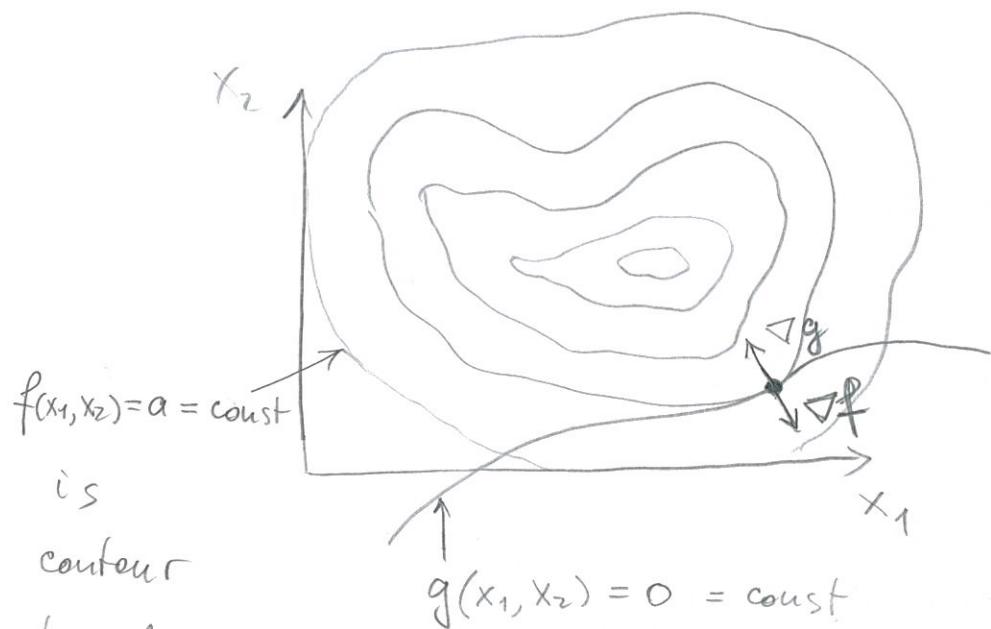
The Mini-Max theorem provides a foundation for computing upper bounds to the exact energies of excited states.

Appendix: Method of Lagrange multipliers

The method of Lagrange multipliers gives a recipe of finding a (local) maximum or minimum of a function of several variables $f(x_1, \dots, x_n)$ subject to equality constraints $g_1(x_1, \dots, x_n) = 0, \dots, g_m(x_1, \dots, x_n) = 0$

For simplicity let us assume $n=2$ and $m=1$, so that the task is

$$\begin{cases} \min_{\{x_1, x_2\}} f(x_1, x_2) \\ g(x_1, x_2) = 0 \end{cases}$$



The gradient of f is perpendicular to its contour lines. The gradient of g is also perpendicular to its contour lines. $g(x_1, x_2) = 0$ is a contour line. Hence for the contour lines of f and g to be parallel (the conditional minima are at such points where the contour lines are parallel) the following must be true

$$\nabla f = \lambda \nabla g \quad \text{where } \lambda \text{ is a constant (could be positive or negative)}$$

It can be seen that if we rather than $f(x)$ minimize the following function

$$F = f - \lambda g$$

with respect to x_1, x_2 as well as with respect to λ the above condition ($\nabla f = \lambda \nabla g$) is automatically met

$$\left. \begin{array}{l} \frac{\partial F}{\partial x_1} = 0 \\ \frac{\partial F}{\partial x_2} = 0 \\ \frac{\partial F}{\partial \lambda} = 0 \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \frac{\partial f}{\partial x_1} = \lambda \frac{\partial g}{\partial x_1} \\ \frac{\partial f}{\partial x_2} = \lambda \frac{\partial g}{\partial x_2} \\ g = 0 \end{array} \right.$$

at the same time at the point we are looking for $g(x_1, x_2) = 0$.

Hence to solve our problem - finding a minimum of a function subject to constraint we can find an unconstrained minimum of $F(x_1, x_2, \lambda)$ with respect to x_1, x_2 , and λ . Quantity λ is called the Lagrange multiplier.

In the case of multiple (m) constraints we will have m Lagrange multipliers $\lambda_1, \dots, \lambda_m$ and we will need to find an unconstrained minimum of

$$F(x_1, \dots, x_n; \lambda_1, \dots, \lambda_m) = f(x_1, \dots, x_n) - \sum_{i=1}^m \lambda_i g_i(x_1, \dots, x_n)$$

Appendix : The Mini-Max Theorem

Let H be a hermitian operator with discrete eigenvalues $E_1 \leq E_2 \leq E_3 \leq \dots$. Let $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_N$ be the eigenvalues of H restricted to subspace \mathcal{V}_N of a linearly independent set of N functions $\{\phi_i\}$. Then

$$E_1 \leq \lambda_1, E_2 \leq \lambda_2, \dots, E_N \leq \lambda_N$$

Proof: Let ω_N be the subspace spanned by the orthonormal eigenstates ψ_1, \dots, ψ_N of operator H . We will first show that there is at least one normalized function in \mathcal{V}_N with the property

$$\langle \phi | H | \phi \rangle \geq E_N$$

Consider the projected function $P\phi$ for any normalized function ϕ in \mathcal{V}_N , where

$$P = \sum_{i=1}^N |\psi_i\rangle \langle \psi_i|$$

There are two possibilities :

- 1) there exists a function ϕ_0 in \mathcal{V}_N such that $P\phi_0 = 0$
- 2) $P\phi \neq 0$ for all functions ϕ in \mathcal{V}_N

In case 1) ϕ_0 is a linear combination of $\phi_{N+1}, \phi_{N+2}, \dots$ and hence the normalized ϕ_0 has the mean value

$$\langle \phi_0 | H | \phi_0 \rangle \geq E_{N+1} \geq E_N$$

In case 2) any two different normalized functions ϕ_i and ϕ_j in \mathcal{V}_N are projected to different functions $P\phi_i$ and $P\phi_j$ in ω_N because otherwise $P(\phi_i - \phi_j) = 0$,

which contradicts the assumption. Namely, any two different normalized functions in \mathcal{V}_N are projected by P to different functions in \mathcal{W}_N . As both \mathcal{V}_N and \mathcal{W}_N have the same dimension, it follows that there must exist a normalized function ϕ in \mathcal{V}_N with the property $P\phi = a\psi_k$ ($a \neq 0$). Then ϕ can be expressed as $a\psi_k + b\psi$ where ψ is a normalized function given as a linear combination of $\psi_{N+1}, \psi_{N+2}, \dots$ and $|a|^2 + |b|^2 = 1$. This function has the mean value

$$\langle \phi | H | \phi \rangle = |a|^2 E_N + |b|^2 \langle \psi | H | \psi \rangle = E_N + |b|^2 (\langle \psi | H | \psi \rangle - E_N) \geq E_N$$

Because λ_N is the largest eigenvalue of H restricted to \mathcal{V}_N we have

$$\lambda_N \geq \langle \phi | H | \phi \rangle \geq E_N$$

Next we can just define the $N-1$ dimensional state space \mathcal{V}_{N-1} to be the set of all those functions in \mathcal{V}_N which are orthogonal to the eigenvector belonging to λ_N and by induction show

$$\lambda_{N-1} \geq E_{N-1} \text{ and so on}$$